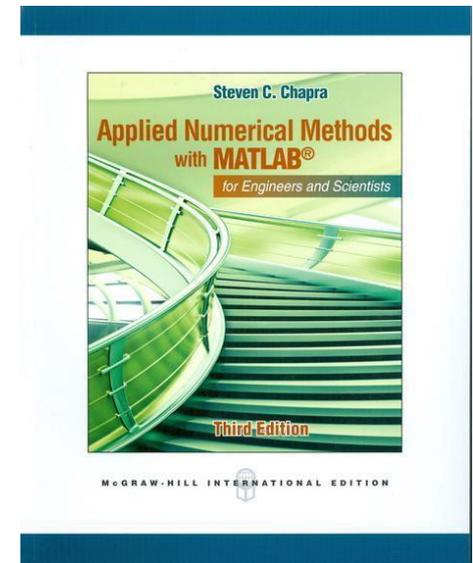


# Numerical Analysis (수치해석)

Course#: 47892  
Mechanical Engineering  
Chung-Ang University

- Instructor
  - Jung Bin In (인정빈), B# 310, R# 529
  - Email: [jbin@cau.ac.kr](mailto:jbin@cau.ac.kr)
  - Homepage: <https://www.sesla.me>
  - Office hour: WED, 14:00 – 16:00
- Prerequisites
  - Engineering Mathematics, Calculus
- Language
  - Korean
- Textbook
  - *Applied Numerical Methods with MATLAB*, Chapra



## ▶ Assessment

- ▶ mid term(45%) / final exam(45%) / homework (5%) / Attendance (0 %)/ Attitude, participation(5%)

## • Exams

~~— Closed book exams~~

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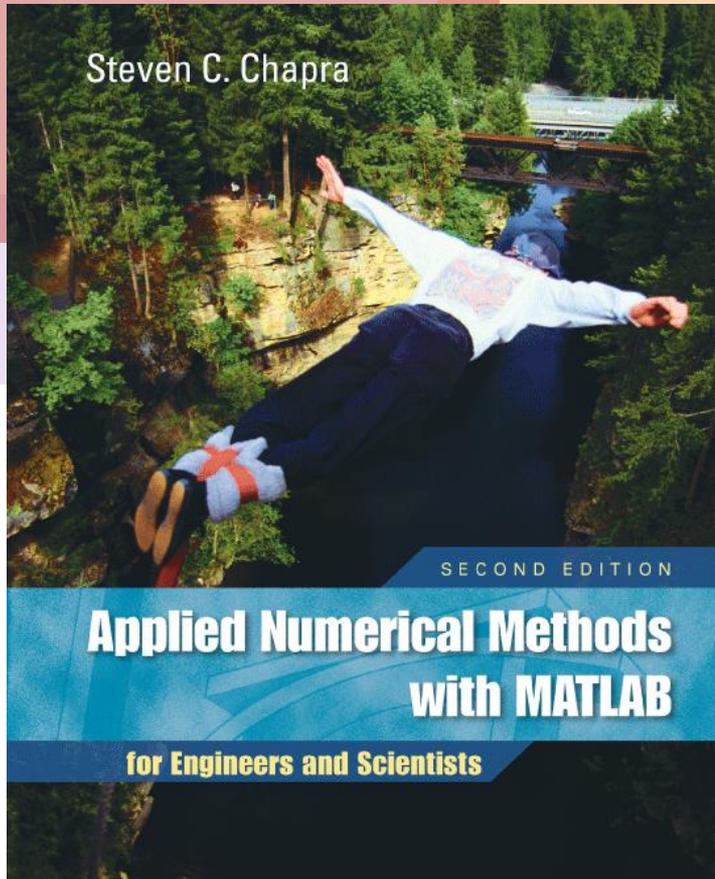
~~— Only the official calculator designated by the department is allowed for the use in exams.~~

— Will necessarily give at least one problem that is very *similar* to homework problems.

— You can be wrong with digits, but you cannot about how to solve. Marking/grading will evaluate every step of your answer.

## ▶ Course schedule (tentative)

Week	Topic	Note
1	Introduction	
2	Roundoff and truncation errors	
3	Bracketing and Open methods	
4	Linear algebraic equations and matrices	
5	Gauss elimination	
6	LU factorization	
7	Matrix inverse and condition	
8	Mid-term exam	midterm exam
9	Iterative methods	
10	Linear regression/Generalized linear least squares	
11	Polynomial interpolations	
12	Piecewise interpolation	
13	Numerical integration	
14	Numerical differentiation	
15	Initial-value problems	
16	Final exam	final exam



# Part 1

## Chapter 1

### Mathematical Modeling, Numerical Methods, and Problem Solving

PowerPoints organized by Dr. Michael R. Gustafson II, Duke University

# Chapter Objectives

- ▶ Learning how mathematical models can be formulated on the basis of scientific principles to simulate the behavior of a simple physical system.
- ▶ Understanding how numerical methods afford a means to generalize solutions in a manner that can be implemented on a digital computer.
- ▶ Understanding the different types of conservation laws that lie beneath the models used in the various engineering disciplines and appreciating the difference between steady-state and dynamic solutions of these models.
- ▶ Learning about the different types of numerical methods we will cover in this book.

# A Simple Mathematical Model

- ▶ A mathematical model can be broadly defined as a formulation or equation that expresses the essential features of a physical system or process in mathematical terms.
- ▶ Models can be represented by a functional relationship between dependent variables, independent variables, parameters, and forcing functions.

# Model Function

$$\text{Dependent variable} = f\left(\begin{array}{l} \text{independent} \\ \text{variables} \end{array}, \text{parameters}, \begin{array}{l} \text{forcing} \\ \text{functions} \end{array}\right)$$

- *Dependent variable* - a characteristic that usually reflects the behavior or state of the system
- *Independent variables* - dimensions, such as time and space, along which the system's behavior is being determined
- *Parameters* - constants reflective of the system's properties or composition
- *Forcing functions* - external influences acting upon the system

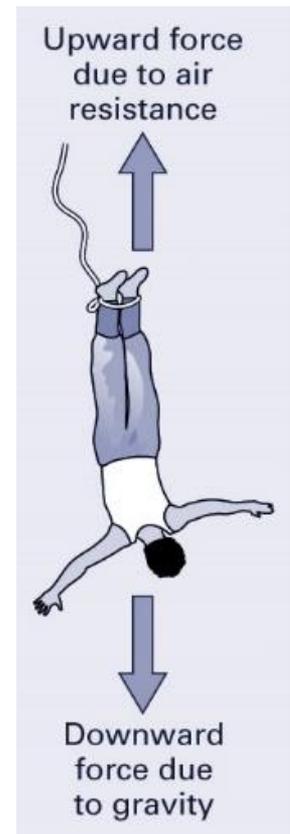


# Model Function Example

- ▶ Assuming a bungee jumper is in mid-flight, an analytical model for the jumper's velocity, accounting for drag, is

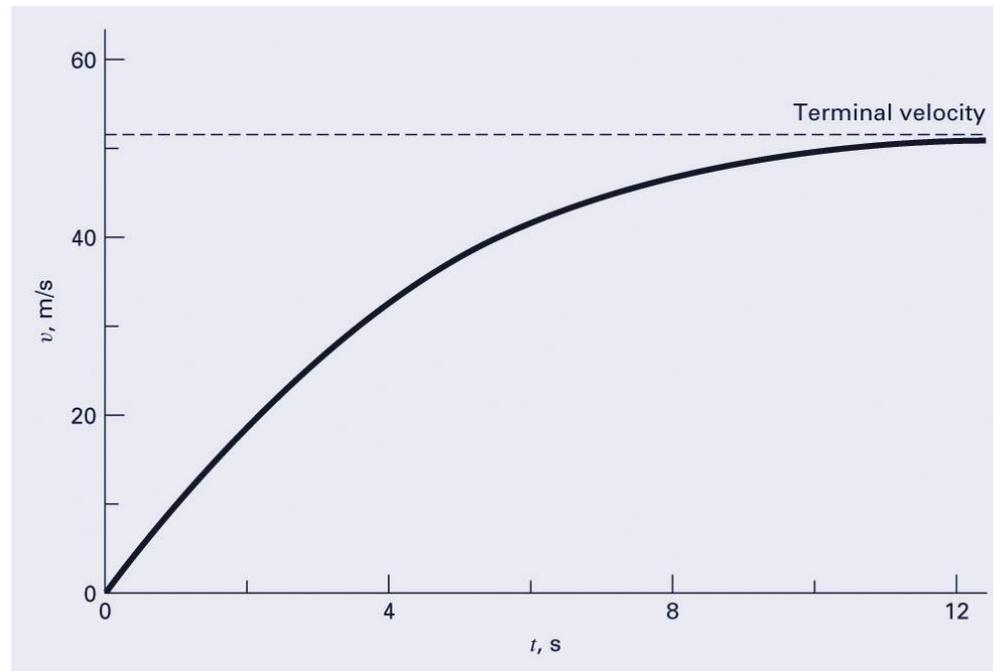
$$v(t) = \sqrt{\frac{gm}{c_d}} \tanh\left(\sqrt{\frac{gc_d}{m}} t\right)$$

- ▶ Dependent variable - velocity  $v$
- ▶ Independent variables - time  $t$
- ▶ Parameters - mass  $m$ , drag coefficient  $c_d$
- ▶ Forcing function - gravitational acceleration  $g$



# Model Results

- ▶ Using a computer (or a calculator), the model can be used to generate a graphical representation of the system. For example, the graph below represents the velocity of a 68.1 kg jumper, assuming a drag coefficient of 0.25 kg/m



# Numerical Modeling

- ▶ Some system models will be given as implicit functions or as differential equations - these can be solved either using analytical methods or numerical methods.
- ▶ Example - the bungee jumper velocity equation from before is the analytical solution to the differential equation

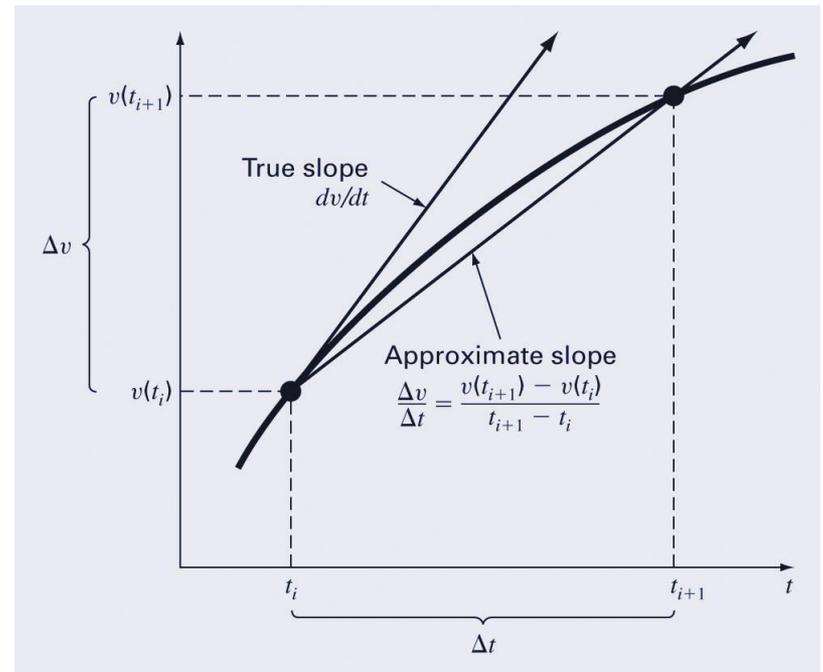
$$\frac{dv}{dt} = g - \frac{c_d}{m} v^2$$

where the change in velocity is determined by the gravitational forces acting on the jumper versus the drag force.

# Numerical Methods

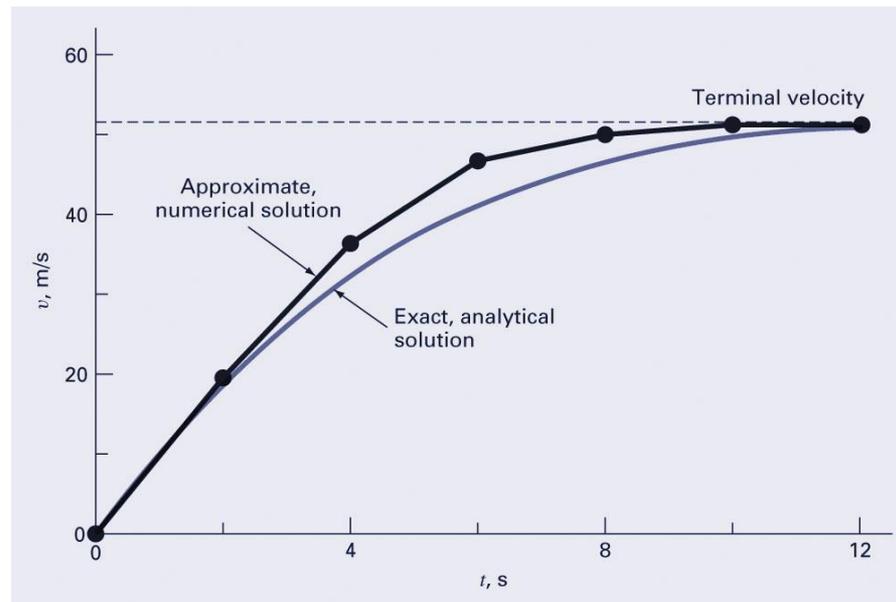
- ▶ To solve the problem using a numerical method, note that the time rate of change of velocity can be approximated as:

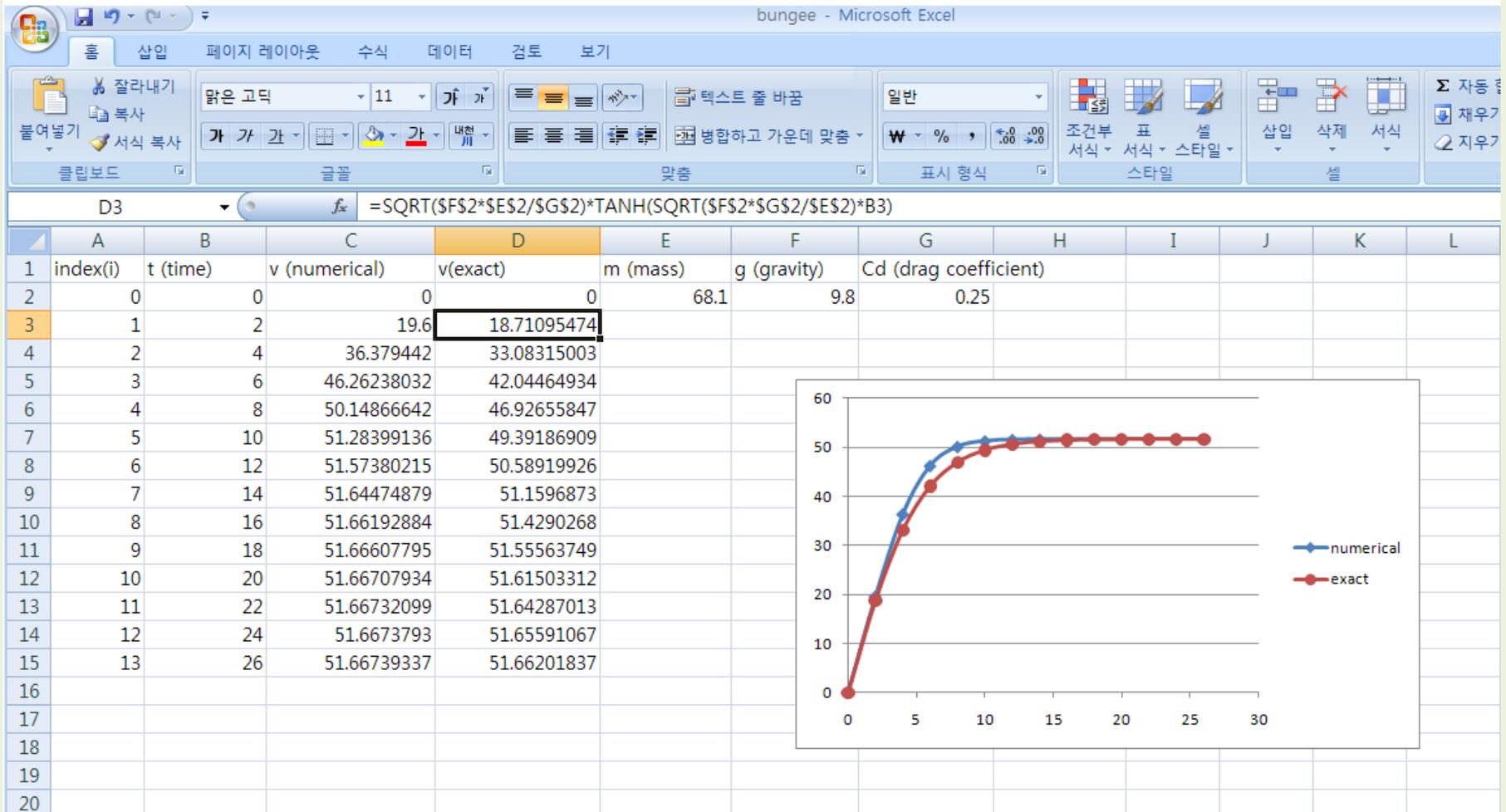
$$\frac{dv}{dt} \approx \frac{\Delta v}{\Delta t} = \frac{v(t_{i+1}) - v(t_i)}{t_{i+1} - t_i}$$



# Numerical Results

- ▶ As shown in later chapters, the efficiency and accuracy of numerical methods will depend upon how the method is applied.
- ▶ Applying the previous method in 2 s intervals yields:

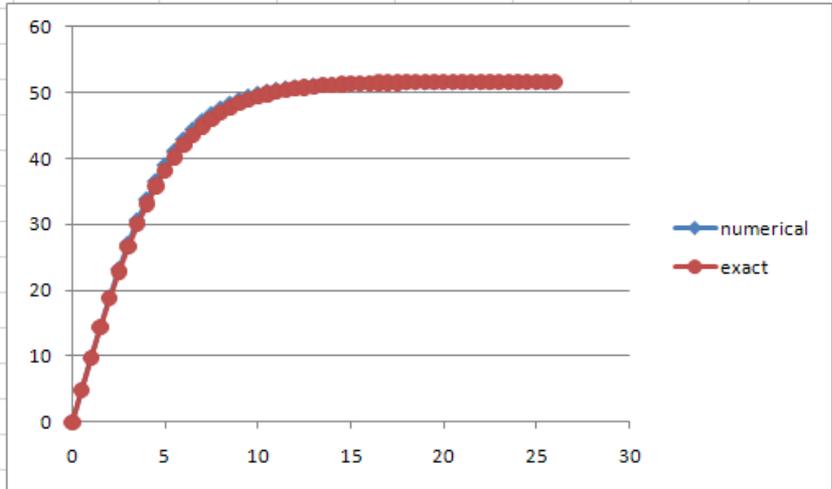




Time step  $(t_{i+1} - t_i) = 2$  second



	A	B	C	D	E	F	G	H	I	J	K	L	M
1	index(i)	t (time)	v (numerical)	v(exact)	m (mass)	g (gravity)	Cd (drag coefficient)						
2		0	0	0	68.1	9.8	0.25						
3		1	0.5	4.9	4.885362253								
4		2	1	9.755928781	9.684143707								
5		3	1.5	14.48122587	14.31579439								
6		4	2	18.99630314	18.71095474								
7		5	2.5	23.23393249	22.81508219								
8		6	3	27.1430815	26.59022791								
9		7	3.5	30.69075611	30.01501402								
10		8	4	33.86182345	33.08315003								
11		9	4.5	36.65715552	35.800981								
12		10	5	39.09065947	38.18457822								
13		11	5.5	41.18581428	40.25680349								
14		12	6	42.97224729	42.04464934								
15		13	6.5	44.48272079	43.57702436								
16		14	7	45.7507229	44.88304249								
17		15	7.5	46.80870997	45.99079734								
18		16	8	47.68694909	46.92655847								
19		17	8.5	48.41285747	47.71430784								
20		18	9	49.01071040	48.37552310								



Time step ( $t_{i+1} - t_i$ ) = 0.5 second

# Bases for Numerical Models

- ▶ Conservation laws provide the foundation for many model functions.
- ▶ Different fields of engineering and science apply these laws to different paradigms within the field.
- ▶ Among these laws are:
  - ▶ Conservation of mass
  - ▶ Conservation of momentum
  - ▶ Conservation of charge
  - ▶ Conservation of energy

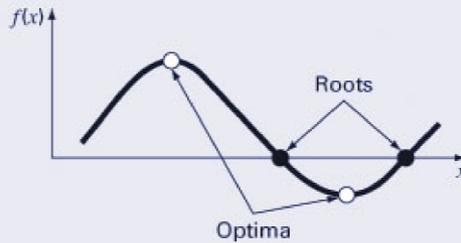
# Summary of Numerical Methods

- ▶ The book is divided into five categories of numerical methods:

## (a) Part 2: Roots and optimization

Roots: Solve for  $x$  so that  $f(x) = 0$

Optimization: Solve for  $x$  so that  $f'(x) = 0$

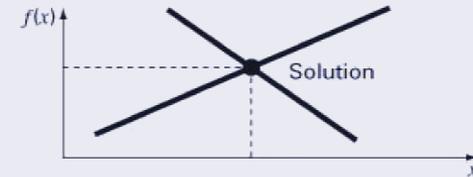


## (b) Part 3: Linear algebraic equations

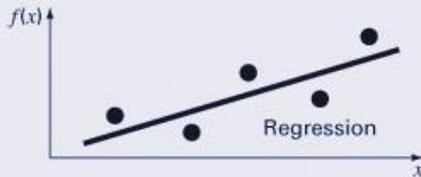
Given the  $a$ 's and the  $b$ 's, solve for the  $x$ 's

$$a_{11}x_1 + a_{12}x_2 = b_1$$

$$a_{21}x_1 + a_{22}x_2 = b_2$$



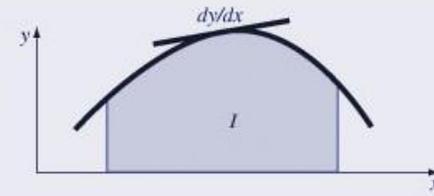
## (c) Part 4: Curve fitting



## (d) Part 5: Integration and differentiation

Integration: Find the area under the curve

Differentiation: Find the slope of the curve



## (e) Part 6: Differential equations

Given

$$\frac{dy}{dt} \approx \frac{\Delta y}{\Delta t} = f(t, y)$$

solve for  $y$  as a function of  $t$

$$y_{i+1} = y_i + f(t_i, y_i)\Delta t$$

